

**Objective Paper-I-2013****Directions:**

Each of the next Ten (10) items consists of two statements, one labeled as the 'Statement (I)' and the other as 'Statement (II)'. You are to examine these two statements carefully and select the answers to these items using the codes given below:

**Codes:**

- (A) Both Statement (I) and Statement (II) are individually true and Statement (II) is the correct explanation of Statement (I).
- (B) Both Statement (I) and Statement (II) are individually true but Statement (II) is NOT the correct explanation of Statement (I).
- (C) Statement (I) is a true but Statement (I) is false.
- (D) Statement (I) is false but Statement (II) is true

1. Statement (I): The Dielectric constant of a substance, under the influence of alternating electric fields is, in general, a 'complex' quantity.  
Statement (II): The 'imaginary' part of the Dielectric constant is a measure of the dielectric loss in the substance.
2. Statement (I): A large number of metals become super-conducting below a certain temperature which is characteristic of the particular metal.  
Statement (II): Super conducting compounds and alloys must have components which are themselves super conducting.
3. Statement (I): Electrostriction occurs due to piezoelectricity which in the reverse effects i.e. the production of polarization on application of mechanical stress if the lattice has no centre of symmetry.  
Statement (II): When an electric field is applied to a substance it becomes polarized, the electrons and nuclei assume new geometric positions and the mechanical dimensions of the substance are altered.
4. Statement (I): By measuring the Hall-effect voltage, one can determine:  
(a) The strength of the field in terms of the current, or  
(b) The current in terms of the fields  
Statement (II): In the case of a semi-conductor, the mobility of the carriers can be determined by using (b), so long as only one kind of carrier is present.
5. Statement (I): In an ac dynamometer type wattmeter the instantaneous value of developed deflecting torque is proportional to the product of voltage and current in the respective coils at the corresponding instant, the constant of proportionality being the same as in the case of dc use.  
Statement (II): The moving system of the meter is prevented by its inertia from following the variations in the deflecting torque which takes place during each cycle, and takes up a position corresponding to the average value of the torque.

6. Statement (I): Electrostatic Wattmeter is not widely used commercially because of its inability to measure power of high value.  
Statement (II): It is used mainly for very small power measurement at high voltages and low power factors.
7. Statement (I): Chopper-stabilized amplifier amplifies direct currents with large gain and excellent dc stability.  
Statement (II): The amplifier is ac coupled and provides very high resistance to direct current.
8. Statement (I): Force and pressure can be measured by using capacitive transducer.  
Statement (II): Capacitive transducer can be used to measure both static and dynamic phenomena
9. Statement (I): A Watt-hour meter must be calibrated at both full rated load as well as at 10% of rated load.  
Statement (II): The source of error at full load is inaccurate damping and at light loads, the torque is not exactly proportional to load.
10. Statement (I): For random error with normal distribution, probable error =  $\pm 0.6745 \sigma$ , where  $\sigma$  is the standard deviation.  
Statement (II): Probable error  $\xi_p$  is the error value where there is a 50% chance that any observation has a random error no greater than  $\pm \xi_p$ .
11. A quantitative relation between induced emf and rate of change of flux linkage is known as  
(A) Maxwell's law (B) Stoke's law  
(C) Lenz's law (D) Faraday's law
12. Two identical coaxial circular loops carry the same direction. If the loops approached each other, then the current in  
(A) each one of them will increase  
(B) both of them will remain the same  
(C) each one of them will decrease  
(D) one will increase while in the other the current will decrease
13. If  $E = 0$  at all points on a closed surface,  
1. The electric flux through the surface is zero  
2. The total charge enclosed by the surface is zero  
3. charge resides on the surface  
(A) 1 and 2 only (B) 1 and 3 only (C) 2 and 3 only (D) 1, 2 and 3

14. A long straight wire carries a current  $I = 10$  A, the magnetic field at a distance of 1.59m is  
 (A)  $0.1 \text{ Am}^{-1}$                       (B)  $1 \text{ Am}^{-1}$                       (C)  $10 \text{ Am}^{-1}$                       (D)  $100 \text{ Am}^{-1}$
15. If the magnetic flux through each turn of the coil consisting of 200 turns is  $(t^2 - 3t)$  milli-Webers, where  $t$  is in seconds, then the induced emf in the coil at  $t = 4$  seconds is  
 (A) -1V                      (B) 1V                      (C) -0.1V                      (D) 0.1V
16. The electrostatic force of repulsion between two  $\alpha$ -particles of charges  $4.0 \times 10^{-19} \text{ C}$  each, and separated by a distance of  $10^{-10} \text{ cm}$  is  
 (Given  $\epsilon_0 = 8.854 \times 10^{-12} \text{ Nm}^2 / \text{Coul}^2$ )  
 (A)  $57.6 \times 10^{-4} \text{ N}$                       (B)  $28.8 \times 10^{-4} \text{ N}$                       (C)  $14.4 \times 10^{-4} \text{ N}$                       (D)  $3.6 \times 10^{-4} \text{ N}$
17. Consider the following statements regarding magnetic materials:
1. A diamagnetic material has no permanent dipole
  2. Paramagnetic material has anti parallel orientation of equal moments with neighboring dipoles
  3. Ferrimagnetic material has anti parallel orientation of unequal moments between neighboring dipoles
  4. Anti ferromagnetic material has negligible interaction between neighboring dipoles.
- Which of those statements are correct?  
 (A) 1 and 2                      (B) 3 and 4                      (C) 2 and 4                      (D) 1 and 3
18. Consider the following statements regarding hysteresis loops of hard and soft magnetic materials:
1. Hysteresis loss of hard magnetic material will be less than that of soft material
  2. Coercivity of hard material will be greater than that of soft material
  3. Retentivity of the two materials will always be equal
- Which of these statements are correct?  
 (A) 1, 2 and 3                      (B) 2 only                      (C) 3 only                      (D) 1 and 3 only
19. The inconsistency of continuity equation for time varying fields was corrected by Maxwell and the correction applied was  
 (A) Ampere's law  $\frac{\partial D}{\partial t}$                       (B) Gauss's law, J  
 (C) Faraday's law  $\frac{\partial B}{\partial t}$                       (D) Ampere's law  $\frac{\partial P}{\partial t}$

20. Loss-tangent in plane waves in lossy dielectrics will be  
 (A) proportional to the Y component of the magnetic field intensity ( $H_Y$ )  
 (B) inversely proportional to the Y component of the magnetic field intensity ( $H_Y$ ) (C) inversely proportional to the X component of the magnetic field intensity ( $H_X$ )  
 (D) proportional to the X component of the magnetic field intensity ( $H_X$ )
21. Transverse Electro-magnetic waves are characterized by  
 (A) During wave propagation in Z-direction, the components of H and E are transverse  $60^\circ$  to the direction of propagation of the waves.  
 (B) During wave propagation in Z-direction, the components of H and E are transverse to the direction of propagation of the waves.  
 (C) During wave propagation in Z-direction, the components of H and E are transverse  $120^\circ$  to the direction of propagation of the waves.  
 (D) None of the above
22. Orientational polarization is  
 (A) inversely proportional to temperature and proportional to the square of the permanent dipole moment  
 (B) proportional to temperature as well as to the square of the permanent dipole moment  
 (C) proportional to temperature and inversely proportional to the square of the permanent dipole moment  
 (D) inversely proportional to temperature as well as to the square of the permanent dipole moment
23. Two media are characterized as:  
 1.  $\epsilon_r = 1, \mu_r = 4$  and  $\sigma = 0$ .  
 2.  $\epsilon_r = 4, \mu_r = 4$  and  $\sigma = 0$   
 Where:  $\epsilon_r$  = relative permittivity,  $\mu_r$  = relative permeability,  $\sigma$  = conductivity  
 The ratio of the intrinsic impedance of the media 2 to media 1 is  
 (A) 2 : 1 (B) 1 : 2 (C) 1 : 1 (D) 2 : 2
24. A transmission line of characteristic impedance  $50\Omega$  is terminated at one end by  $+j50\Omega$ . The VSWR produced by the line is  
 (A) +1 (B) 0 (C)  $\infty$  (D) +j
25. A loss-less transmission line having characteristic impedance  $Z_0$  is terminated in a load of  $Z_R$ . IF the value of  $Z_R$  is exactly half of  $Z_0$  then reflection coefficient  $\Gamma_L$  is  
 (A)  $\frac{1}{3}$  (B)  $\frac{2}{3}$  (C)  $-\frac{1}{3}$  (D)  $-\frac{2}{3}$

26. Volt-box is basically a device used for
- (A) measuring the voltage
  - (B) extending the range of voltmeter
  - (C) extending the voltage range of the potentiometer
  - (D) measuring power
27. To minimize voltmeter loading
- (A) Voltmeter operating current has to be very small
  - (B) Voltmeter operating current has to be very high
  - (C) Resistance connected in series with the coil should be low
  - (D) Resistance connected in parallel with the coil should be high
28. A 3-phase moving coil type power factor meter has three fixed and symmetrically spaced current coils, inside of which are three other similarly placed moving potential coils. While in operation, rotating magnetic field is produced.
- (A) in the current coils but not in the potential coils
  - (B) in the potential coils but not in the current coils
  - (C) in both potential coils and the current coils
  - (D) in neither the potential coils nor the current coils.
29. In a low power factor wattmeter, sometimes compensating coil is connected in order to
- (A) neutralize the capacitive effect of pressure coil
  - (B) compensate for inductance of pressure coil
  - (C) compensate for power loss in the pressure coil
  - (D) reduce the error caused by eddy current
30. The current and potential coil of a watt-meter were accidentally interchanged while connecting. After energizing the circuit, it was observed that the watt-meter did not show the reading. This would be due to
- (A) damage done to the potential coil
  - (B) damage done to the current coil
  - (C) damage done to both potential and current coils
  - (D) loose contact.
31. A current  $i = 5 + 14.14 \sin(314t + 45^\circ)$  is passed through a centre-zero PMMC, hot-wire, and moving-iron instrument, the respective readings are
- (A)  $-5, 15$  and  $\sqrt{125}$
  - (B)  $5, \sqrt{125}$  and  $\sqrt{125}$
  - (C)  $-5, \sqrt{125}$  and  $19.14$
  - (D)  $5, 10$  and  $10$

32. The galvanometer is protected during transport by  
(A) connecting critical damping resistance across the galvanometer terminals  
(B) shorting the galvanometer terminals  
(C) keeping the galvanometer terminals open- circuited  
(D) connecting a capacitor across the galvanometer terminals
33. A frequency counter needs to measure a frequency of 15 Hz. Its signal gating time is 2s. What is the percentage accuracy of the counter, taking into account the gating error?  
(A) 3.33%                      (B) 13.33%                      (C) 98.67%                      (D) 96.67%
34. Wagner's earthing devices is used in A.C. bridges for  
(A) shielding the bridge element  
(B) eliminating the stray of electro static field effects  
(C) eliminating the effect of earth capacitances  
(D) eliminating the effect of inter-component capacitances
35. A bridge circuit works at a frequency of 2 kHz. The following can be used as detectors for detection of null conditions in the bridges.  
(A) Vibration galvanometers and Headphones.  
(B) Headphones and tunable amplifiers  
(C) Vibration galvanometers and tunable amplifiers  
(D) Vibration galvanometers, Headphones and Tunable amplifier
36. A current transformer has a phase error of  $+3^\circ$ . The phase angle between the primary and secondary current is  
(A)  $3^\circ$                       (B)  $177^\circ$                       (C)  $180^\circ$                       (D)  $183^\circ$
37. Electronic voltmeters which use rectifiers employ negative feedback. This is done  
(A) to increase the overall gain  
(B) to improve the stability  
(C) to overcome the non-linearity of diodes  
(D) to increase the band width
38. Creep error may occur in induction type energy meter due to  
(A) incorrect position of brake magnet  
(B) incorrect adjustment of position of shading band  
(C) over voltage across voltage coil  
(D) increase in temperature
39. An 8-bit successive approximation DVM of 5V range is used to measure 1.2v. The contents of the SAR after 5 clock pulses is  
(A) 01010000                      (B) 00111100                      (C) 00111000                      (D) 00110111

40. In a digital voltmeter, the oscillator frequency is 400 kHz. A ramp voltage to be measured by this voltmeter falls from 8V to 0V in 20 ms. The number of pulses counted by the counter is  
(A) 8000                      (B) 4000                      (C) 3200                      (D) 1600
41. While using a frequency counter for measuring frequency, two modes of measurement are possible.  
(i) Period mode  
(ii) Frequency mode  
There is a 'cross-over frequency' below which the period mode is preferred. Assuming the crystal oscillator frequency to be 4 MHz the cross-over frequency is given by  
(A) 8 MHz                      (B) 2 MHz                      (C) 2 kHz                      (D) 1 kHz
42. Which of the following instrument will be used to measure a small current of very high frequency?  
(A) Electrodynamometer ammeter  
(B) Moving coil galvanometer  
(C) Thermocouple type instrument  
(D) Induction type instrument
43. In a digital data acquisition system, a scanner-multiplexer  
(A) scans the printed diagram and converts it into digital data.  
(B) accepts multiple digital inputs and output any one of them with select lines  
(C) accepts multiple analog inputs and sequentially connects them to an ADC  
(D) checks the correct functioning of the modulus one by one
44. The number of bits of A/D converter required to convert an analog input in the range of 0-5 volt to an accuracy of 10 mV is  
(A) 8                      (B) 9                      (C) 10                      (D) 16
45. The drift velocity of electron in Silicon  
(A) is proportional to electric field for all values of electric field  
(B) is independent of electric field  
(C) increases at lower values and decreases at higher values of electric field  
(D) increases linearly with electric field at low values and gradually saturates at higher values of electric field.
46. The number of  $2\mu\text{F}, 300\text{V}$  capacitors needed to obtain a capacitance value of  $2\mu\text{F}$  rated for 1200V is  
(A) 16                      (B) 12                      (C) 10                      (D) 08

47. Behaviour of conductors, semiconductors and insulators is explained on the basis of  
(A) atomic structure (B) molecular structure  
(C) energy band structure (D) all of the above
48. In general for a superconductor, which of the following statements is true?  
(A) A superconductor is a perfect paramagnetic material with the magnetic susceptibility equals to positive unity.  
(B) A superconductor is a perfect diamagnetic material with the magnetic susceptibility equals to negative one.  
(C) A superconductor is a perfect ferromagnetic susceptibility equals to positive one.  
(D) A superconductor is a perfect piezoelectric material with the magnetic susceptibility equals to negative unity.
49. Ferro-electric material have a  
(A) high dielectric constant which varies non-linearly  
(B) low dielectric constant and is non-linear  
(C) high dielectric constant which varies linearly  
(D) low dielectric constant but linear
50. In the magnetic core the electromotive forces (emf) induced in accordance with Faraday's law of electromagnetic induction give rise to  
(A) Eddy current (B) Excitation current  
(C) Armature current (D) Field current
51. Consider the following characterizing parameters of a material  
1. Magnetic permeability  
2. Electron relaxation time  
3. Electron effective mass  
4. Energy band gap  
In case of metals, increase in one of the above parameter decreases its conductivity, while increase in another increases the conductivity. These are respectively  
(A) 1 and 3 (B) 3 and 2 (C) 4 and 3 (D) 1 and 2
52. Some magnetic materials may be classified on the basis of  
1. Susceptibility  
2. Saturation  
3. Spin arrangement  
4. Nature if hysteresis loop  
5. Domain structure  
6. Critical temperature above which it behaves as a paramagnetic material  
Which of these can be used to distinguish between ferri and ferromagnetic materials?  
(A) 1, 3 and 4 only (B) 2, 3 and 6 only (C) 3, 4 and 5 only (D) 1,2,3,4,5 and 6

53. Magnetism is mainly due to only electron spin around their own axis in case of
- (A) diamagnetic materials
  - (B) paramagnetic materials
  - (C) ferromagnetic materials
  - (D) paramagnetic and diamagnetic materials
54. For paramagnetic materials, the relative permeability is
- (A) less than unity but magnetic susceptibility is relatively small and positive
  - (B) greater than unity and magnetic susceptibility is relatively small but positive
  - (C) equal to unity and magnetic susceptibility is large but positive
  - (D) less than unity but magnetic susceptibility is relatively large and positive
55. Permalloy and Mumetal are examples of
- (A) Silicon and Iron alloys
  - (B) Nickel and Iron alloys
  - (C) Cobalt and Iron alloys
  - (D) Permanent magnet materials
56. When a Ferromagnetic substance is magnetized, the phenomenon of 'magnetostriction' causes
- (A) increase in the body temperature
  - (B) change in the permeability of the substance
  - (C) small changes in its dimensions
  - (D) decrease in the saturation flux density
57. The resistivity of 'ferrites' is very much higher than that of the Ferromagnetic metals, because
- (A) Ferrites are chemical compounds and the electrons in them are subjects to the restraint of valence forces
  - (B) Ferrites have a low eddy current loss
  - (C) Ferrites have a non-homogenous molecular structure
  - (D) Ferrites have varying flux-density inside the core
58. When the temperature exceeds the transition temperature, a ferromagnetic material becomes similar to
- (A) anti-ferromagnetic material
  - (B) diamagnetic material
  - (C) ferromagnetic material
  - (D) paramagnetic material
59. Einstein relation is referred between
- (A) the diffusion constant and the mobility
  - (B) the conduction and diffusion currents
  - (C) the conduction and diffusion voltages
  - (D) none of the above

60. In a piezoelectric crystal oscillator, the oscillation or tuning frequency is linearly proportional to the
- mass of the crystal
  - square root of the mass of the crystal
  - square of the mass of the crystal
  - inverse of the square root of the mass of the crystal
61. Which of the following are piezoelectric substances?
- Barium Titanate
  - Lead Titanate
  - Lead Zirconate
  - Cadmium Sulphate
- (A) 1,2 and 4                      (B) 1,3 and 4                      (C) 1, 2 and 3                      (D) 2, 3 and 4
62. Consider the following statements:
- Fermi level in a p-type semiconductor lies close to the top of the valence band
  - The forbidden energy in Germanium at 0°K is exactly 0.75 eV.
  - When a p-n junction is reverse biased, then electrons and holes move away from the junction.
- Which of these statements are correct?
- (A) 1, 2 and 3                      (B) 1 and 2 only                      (C) 2 and 3 only                      (D) 1 and 3 only
63. A second order system is described by  $2\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 8y = 8x$ .
- The damping ratio of the system is
- (A) 0.1                      (B) 0.25                      (C) 0.333                      (D) 0.5
64. When deriving the transfer function of a linear element
- both initial conditions and loading are taken into account
  - initial conditions are taken into account but the element is assumed to be not loaded
  - initial conditions are assumed to be zero but loading is taken into account
  - initial conditions are assumed to be zero and the element is assumed to be not loaded
65. Consider the following statements regarding advantages of closed loop negative feedback control systems over open loop system.
- The overall reliability of the closed loop system is more than that of open loop system.
  - The transient response in a closed loop system decays more quickly than in open loop system.
  - In an open loop system, closing of the loop increases the overall gain of the system.
  - In the closed loop system, the effect of variation of component parameters on its performance is reduced.
- Which of these statements are correct?
- (A) 1 and 2                      (B) 1 and 3                      (C) 2 and 4                      (D) 3 and 4

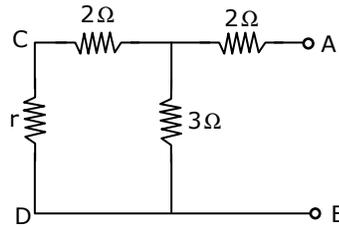
66. A forcing function  $(t^2 - 2t)u(t-1)$  is applied to a linear system. The L-transform of the forcing function is
- (A)  $\frac{2-s}{s^3}e^{-2s}$       (B)  $\left(\frac{1-s^2}{s}\right)e^{-s}$       (C)  $\frac{1}{s}e^{-s} - \frac{1}{s^2}e^{-2s}$       (D)  $\left(\frac{2-s^2}{s^3}\right)e^{-s}$
67. An open loop TF of a unity feedback system is given by  $G(s) = \frac{1}{(s+2)^2}$ . The closed loop transfer function will have poles at
- (A)  $-2, -2$       (B)  $-2, -1$       (C)  $-2+j, -2-j$       (D)  $-2, 2$
68. Damping ratio  $\xi$  and peak overshoot  $M_p$  are measures of
- (A) relative stability      (B) absolute stability  
(C) speed of response      (D) steady state error
69. In control systems, excessive bandwidth is **not** employed because
- (A) noise is proportional to bandwidth  
(B) it leads to low relative stability  
(C) it leads to slower time response  
(D) noise is proportional to the square of the bandwidth
70. The transfer function of a system is  $\frac{1}{1+sT}$ . The input to this system is the ramp function,  $tu(t)$ . The output would track this system with an error given by
- (A) zero      (B)  $\frac{T}{2}$       (C)  $T$       (D)  $\frac{T^2}{2}$
71. For a critically damped second order system, if gain constant (K) is increased, the system behavior
- (A) becomes oscillatory      (B) becomes under damped  
(C) becomes over damped      (D) shows no change
72. A unit impulse response of a second order system is  $\frac{1}{6}e^{-0.8t} \sin(0.6t)$ . Then natural frequency and damping ratio of the system are respectively
- (A) 1 and 0.6      (B) 1 and 0.8      (C) 2 and 0.4      (D) 2 and 0.3
73. Consider the following statements about Routh-Hurwitz criterion:  
If all the elements in one row of Routh array are zero, then there are
1. Pairs of conjugate roots on imaginary axis
  2. Pairs of equal roots with opposite sign
  3. Conjugate roots forming a quadrate in the s-plane

- Which of these statements are correct?
- (A) 1 and 2 only (B) 1 and 3 only  
(C) 2 and 3 only (D) 1, 2 and 3
74. The characteristic equation of a control system is given by  
 $s(s+4)(s+5)(s+6) + K(s+3) = 0$   
 The number of asymptotes and the centroid of the asymptotes of this control system are  
 (A) 3 and (4,0) (B) -3 and (-4,0)  
 (C) -3 and (-12,0) (D) 3 and (-4,0)
75. An effect of Phase-lag compensation on servo-system performance is that  
 (A) for a given relative stability, the velocity constant is increased  
 (B) for a given relative stability, the velocity constant is decreased  
 (C) the bandwidth of the system is increased  
 (D) the time response of the system is made faster
76. The system matrix of a linear time invariant continuous time system is given by  

$$A = \begin{bmatrix} 0 & -1 \\ -4 & -5 \end{bmatrix}$$
  
 What are the roots of the characteristic equation?  
 (A) -1, -4 (B) -1, -5 (C) -4, -5 (D) 0, -1
77. In a closed loop system for which the output is the speed of a motor, the output rate control can be used to  
 (A) reduce the damping of the system  
 (B) limit the torque output of the motor  
 (C) limit the speed of the motor  
 (D) limit the acceleration of the motor
78. A transfer function has its zero in the right half of the s-plane. The function  
 (A) is positive real (B) is minimum phase  
 (C) will give stable impulse response (D) is non-minimum phase
79. If the s-plane counter enclose 3-zeros and 2-poles counter will encircle the origin of q(s) plane  
 (A) once in clockwise direction  
 (B) once in counter clockwise direction  
 (C) thrice in clockwise direction  
 (D) twice in counter clockwise direction

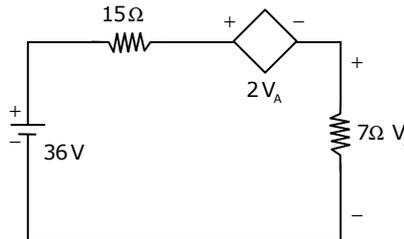
80. For the circuit shown above the value of  $r$  connected between C and D is such that equivalent resistance of the circuit by looking into circuit through terminals A and B is  $r$  only. Then the value of  $r$  is

- (A)  $2\ \Omega$   
(B)  $4\ \Omega$   
(C)  $3\ \Omega$   
(D)  $6\ \Omega$



81. The power dissipated in the controlled source of the network shown is

- (A) 36 W  
(B) 15 W  
(C) 07 W  
(D) 14 W



82. The resistance of a 1 kW electric heater when energized by a 230 V 1-phase AC is  
(A)  $52.9\ \Omega$                       (B)  $230\ \Omega$                       (C)  $1000\ \Omega$                       (D)  $4.2\ \Omega$

83. If an ideal voltage source and ideal current source are connected in series the combination

- (A) has the same properties as a current source alone  
(B) has the same properties as a voltage source alone  
(C) has the same properties as the source which has a higher value  
(D) results in the branch being redundant.

84. A parallel plate capacitor of area  $A\ \text{cm}^2$  and separating distance  $a\ \text{cm}$  is dipped in ethyl alcohol up to a depth of  $\frac{a}{2}$ . Given the dielectric constant  $\epsilon_r$  of ethyl alcohol to be 25, the ratio of capacitance after dipping to that before dipping would be

- (A)  $\frac{26}{50}$                       (B)  $\frac{45}{50}$                       (C)  $\frac{50}{26}$                       (D)  $\frac{3}{1}$

85. A network N consists of resistors, independent voltage and current sources. The value of its determinant based on the loop analysis:

- (1) Cannot be negative  
(2) Cannot be zero  
(3) Is independent of the value of voltage and current sources  
(4) Dependent on the values of the resistances and the voltage and current sources.  
(A) 1, 2 and 3                      (B) 1, 2 and 4                      (C) 1, 3 and 4                      (D) 2, 3 and 4

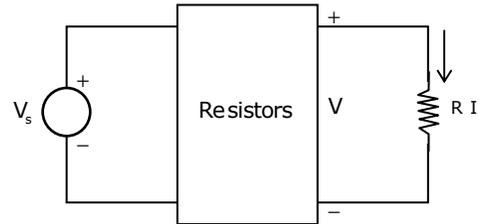
86. In the circuit shown above, for different values of  $R$ , the values of  $V$  and  $I$  are given, other elements remaining the same.

When  $R = \infty$ ,  $V = 5V$

When  $R = 0$ ,  $I = 2.5A$

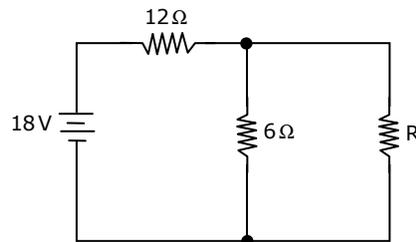
When  $R = 3 \Omega$ , the value of  $V$  is given by

- (A) 1 V                      (B) 5 V  
(C) 3 V                      (D) 2 V



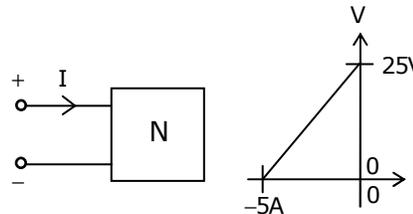
87. In the circuit shown below, the maximum power absorbed by the load resistance  $R_L$  is

- (A) 1.5 W  
(B) 2.25 W  
(C) 2.5 W  
(D) 5 W



88. The voltage-current relationship feeding the network  $N$  is shown in the below figure. The Thevenin's equivalent of network  $N$  will have  $V_{Th}$  and  $R_{Th}$  as

- (A) 5V and  $25 \Omega$   
(B)  $-25V$  and  $5 \Omega$   
(C)  $25V$  and  $-5 \Omega$   
(D)  $25V$  and  $5 \Omega$



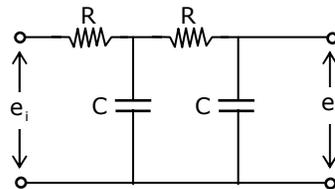
89. An A.C. source of voltage  $E_s$  and an internal impedance of  $Z_s = (R_s + jX_s)$  is connected to a load of impedance  $Z_L = (R_L + jX_L)$ . Consider the following conditions in this regard:

1.  $X_L = X_s$  if only  $X_L$  is varied
2.  $X_L = -X_s$  if only  $X_L$  is varied
3.  $R_L = \sqrt{R_s^2 + (X_s + X_L)^2}$  if only  $R_L$  is varied
4.  $|Z_L| = |Z_s|$ , if the magnitude alone of  $Z_L$  is varied, keeping the phase angle fixed.

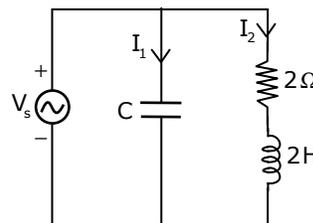
The valid conditions for maximum power transfer from the source to the load are

- (A) 1, 2, 3 and 4                      (B) 1, 2, and 3 only  
(C) 1 and 4 only                      (D) 2, 3 and 4 only

90. Unit impulse response of a given system is  $C(t) = -4e^{-t} + 6e^{-2t}$ . The step response of  $t \geq 0$  is
- (A)  $-3e^{-2t} + 4e^{-t} + 1$  (B)  $3e^{-2t} + 4e^{-t} + 1$   
 (C)  $-3e^{-2t} - 4e^{-t} + 1$  (D)  $3e^{-2t} + 4e^{-t} - 1$
91. Elements R, L and C are connected in parallel. The impedance of the parallel combination can be expressed as  $Z(s) = \frac{10s}{s^2 + s + 400}$ . The value of the individual elements R, L and C are
- (A)  $10\Omega, 40H$  and  $0.1F$  (B)  $4\Omega, 1H$  and  $0.1F$   
 (C)  $10\Omega, \frac{1}{40}H$  and  $0.1F$  (D)  $1\Omega, 40H$  and  $10F$
92. A first order linear system is initially relaxed for a unit step signal  $u(t)$ , the response is  $V(t) = (1 - e^{-3t})$ , for  $t > 0$ . If a signal  $3u(t) + \delta(t)$  is applied to the same system, the response is
- (A)  $(3 - 6e^{-3t})u(t)$  (B)  $(3 - 3e^{-3t})u(t)$  (C)  $3u(t)$  (D)  $(3 + 3e^{3t})u(t)$
93. The transfer function of the network shown below is



- (A)  $\frac{1}{s^2T^2 + 2ST + 1}$  (B)  $\frac{1}{s^2T^2 + 3ST + 1}$   
 (C)  $\frac{1}{s^2T^2 + ST + 1}$  (D)  $\frac{1}{s^2T^2 + 1}$
94. In the network shown below  $V_s = 4\cos 2t$ . The value of C is so chosen that the circuit impedance is maximum. Then  $I_1$  leads  $I_2$  by



- (A)  $45^\circ$   
 (B)  $90^\circ$   
 (C)  $0^\circ$   
 (D)  $135^\circ$

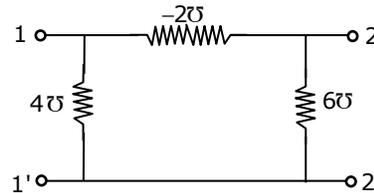
95. A series RLC circuit has a bandwidth of 300 rad/sec at a resonant frequency of 3000 rad/sec when excited by a voltage source of 100V. The inductance of the coil is 0.1 H. The value of R and the voltage across C are respectively.
- (A)  $10\Omega$  and 100V (B)  $30\Omega$  and 100V  
(C)  $30\Omega$  and 1000V (D)  $300\Omega$  and 1000V

96. The circuit comprises a coil of resistance R and inductance L, in parallel with an ideal capacitor C. At the resonant frequency, the impedance of the parallel combination is
- (A) R (B)  $\frac{LC}{R}$  (C)  $\frac{L}{RC}$  (D)  $\infty$

97. In RLC circuits, the current at resonance is
- (A) Maximum in series RLC and minimum in parallel RLC circuit  
(B) Maximum in parallel circuit and minimum in series circuit  
(C) Maximum in both circuits  
(D) Minimum in both circuits

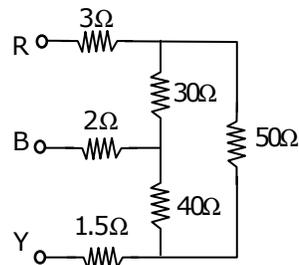
98. For the two port network as shown below, the parameters  $h_{11}$  and  $h_{21}$  are

- (A)  $1\Omega$  and  $2\Omega$   
(B)  $2\Omega$  and 1  
(C) 1 and  $\frac{1}{2}\Omega$   
(D)  $\frac{1}{2}\Omega$  and 1



99. A 3-phase distribution network is as shown above. The resistance across the terminals RB, BY and RY are

- (A)  $25.5\Omega$ ,  $31.2\Omega$  and  $33.6\Omega$   
(B)  $27.5\Omega$ ,  $30.17\Omega$  and  $33.67\Omega$   
(C)  $28.5\Omega$ ,  $32.3\Omega$  and  $34.5\Omega$   
(D)  $21.2\Omega$ ,  $42.3\Omega$  and  $45.6\Omega$



100. A 3-phase load of 0.8 pf lag is supplied from a balanced 3-phase supply of phase sequence RYB. With  $V_{YB}$  as reference the current  $I_R$  will (Given  $\cos^{-1}(0.8) = 36.76^\circ$ )
- (A) In - phase with  $V_{YB}$  (B) Lag  $V_{YB}$  by  $36.76^\circ$   
(C) Lead  $V_{YB}$  by  $53.14^\circ$  (D) Lag  $V_{YB}$  by  $53.14^\circ$

101. A 2-port network is represented by the following equations:

$$V_1 = 60I_1 + 20I_2, \quad V_2 = 20I_1 + 40I_2$$

The ABCD parameters of the above network would be

- (A)  $\begin{bmatrix} 2 & \frac{1}{20} \\ 3 & 100 \end{bmatrix}$       (B)  $\begin{bmatrix} 100 & 3 \\ 2 & \frac{1}{20} \end{bmatrix}$       (C)  $\begin{bmatrix} 100 & 20 \\ 6 & 3 \end{bmatrix}$       (D)  $\begin{bmatrix} 3 & 100 \\ \frac{1}{20} & 2 \end{bmatrix}$

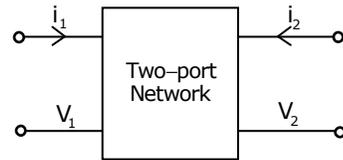
102. Two coupled coils with  $L_1 = L_2 = 0.6$  H have a coupling coefficient of  $K=0.8$ . The turns ratio

$$\frac{N_1}{N_2}$$
 is

- (A) 4      (B) 2      (C) 1      (D) 0.5

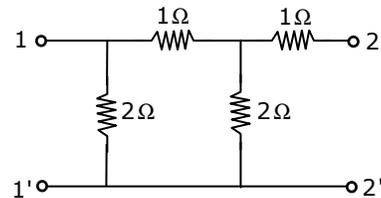
103. The terminal voltage and current of a two-port network are indicated on the below figure. If the two-port is reciprocal, then

- (A)  $\frac{Z_{12}}{Y_{12}} = Z_{12}^2 - Z_{11} \cdot Z_{22}$       (B)  $Z_{12} = \frac{1}{Y_{22}}$   
(C)  $h_{12} = h_{21}$       (D)  $AD-BC=0$



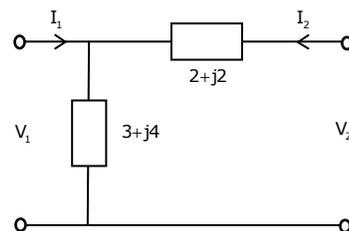
104. The Z-parameters of the 2-port network as shown below are

- (A)  $\begin{bmatrix} \frac{11}{5} & \frac{4}{5} \\ \frac{4}{5} & \frac{6}{5} \end{bmatrix}$       (B)  $\begin{bmatrix} \frac{6}{5} & \frac{4}{5} \\ \frac{4}{5} & \frac{11}{5} \end{bmatrix}$   
(C)  $\begin{bmatrix} \frac{4}{5} & \frac{6}{5} \\ \frac{11}{5} & \frac{4}{5} \end{bmatrix}$       (D)  $\begin{bmatrix} \frac{4}{5} & \frac{4}{5} \\ \frac{11}{5} & \frac{6}{5} \end{bmatrix}$



105. The Z-parameter matrix of the two-port network as shown below is

- (A)  $\begin{bmatrix} 3+j4 & 2+j2 \\ 2+j2 & 5+j6 \end{bmatrix}$       (B)  $\begin{bmatrix} 3+j4 & 3+j4 \\ 3+j4 & 5+j6 \end{bmatrix}$   
(C)  $\begin{bmatrix} 2+j2 & 3+j4 \\ 2+j2 & 5+j6 \end{bmatrix}$       (D)  $\begin{bmatrix} 3+j4 & 2+j2 \\ 1+j2 & 3+j4 \end{bmatrix}$



106. In the two-wattmeter method of measuring 3-phase power, the wattmeters indicate equal and opposite readings when load power factor is

- (A) 90 leading      (B) 90 lagging      (C) 30 leading      (D) 30 lagging



113. If one of the control springs of a permanent magnet coil ammeter is broken, then on being connected it will read  
 (A) Zero (B) Half of the correct value  
 (C) Twice of the correct value (D) An infinite value
114. A  $0.5 \Omega$  resistance is required to be connected in parallel to a moving coil instrument whose full scale deflection is 1 mA; so that this instrument can measure 10 mA current. Internal resistance of this instrument is  
 (A)  $5.0 \Omega$  (B)  $4.5 \Omega$  (C)  $2.25 \Omega$  (D)  $0.45 \Omega$
115. The working of a PMMC (Permanent magnet moving coil) meter is described by a second order differential equation  $J \frac{d^2\theta}{dt^2} + D \frac{d\theta}{dt} + S^l \theta = T$  Where  
 $J$  = Moment of inertia of the system,  $D$  = Damping coefficient,  
 $S^l$  = Spring constant  $\theta$  = Angular deflection and  
 $T$  = Activating torque. Assuming  $D = 0$ , undamped natural angular frequency is  
 (A)  $\sqrt{\frac{S}{J}}$  (B)  $\sqrt{\frac{J}{S}}$  (C)  $\frac{1}{\sqrt{JS}}$  (D)  $\frac{1}{2\mu \sqrt{JS}}$
116. For a certain dynamometer ammeter the mutual inductance ( $M$ ) varies with deflection  $\theta^\circ$  as  $M = -6\cos(\theta + 30^\circ)$  mH. Find the deflecting torque produced a direct current of 50 mA corresponding to a deflection of  $60^\circ$   
 (A) 10 N-m (B) 20 N-m (C)  $15 \mu\text{N} - \text{m}$  (D)  $1.5 \mu\text{N} - \text{m}$
117. An 1-m Amp,  $50 \Omega$  Galvanometer is required to measure 5 Amp (full scale). Find out the value of resistance to be added, across (shunt) the Galvanometer to accomplish this measurement.  
 (A)  $10 \Omega$  (B)  $0.01 \Omega$  (C)  $1.0 \Omega$  (D)  $0.001 \Omega$
118. The voltage sensitivities of Barium Titanate and Quartz are respectively  $12 \times 10^{-3} \text{Vm} / \text{N}$  and  $50 \times 10^{-3} \text{Vm} / \text{N}$ . Their respective permittivities are  $12.5 \times 10^{-9} \text{F} / \text{m}$  and  $40.6 \times 10^{-12} \text{F} / \text{m}$ . What are their charge sensitivities?  
 (A)  $1.04 \times 10^6 \text{C} / \text{N}$  and  $1.23 \times 10^9 \text{C} / \text{N}$   
 (B)  $150 \text{pC} / \text{N}$  and  $2 \text{pC} / \text{N}$   
 (C)  $24.5 \text{pC} / \text{N}$  and  $90.6 \text{pC} / \text{N}$   
 (D)  $0.9 \times 10^6 \text{C} / \text{N}$  and  $1.23 \times 10^9 \text{C} / \text{N}$

119. In two-wattmeter method of measuring power in a balanced 3-phase circuit, the readings of the two wattmeters are in the ratio of 1 : 2, the circuit power factor is

- (A)  $\frac{1}{\sqrt{2}}$                       (B)  $\frac{1}{2}$                       (C)  $\frac{\sqrt{3}}{2}$                       (D) 1

120. Consider the following statements:

Adjustment is required in an induction type energy meter in the following manner so that it can be compensated for slowdown of speed on the specified load due to some unspecified reason:

1. Adjusting the position of braking magnet and moving it away from the centre of the disc.
2. Adjusting the position of braking magnet and moving it closer to the centre of the disc.
3. Adjusting the load.

Which of these statements are correct?

- (A) 1, 2 and 3                      (B) 1 only                      (C) 2 only                      (D) 3 only